

Overview

Welcome to the Core Box Integrator guide. This document serves as a comprehensive guide to using, updating and integrating the Core Box system. It starts with an overview of Core Box and its main functions, followed by detailed descriptions of its key features and variants. You will find explanations of the LED patterns, ignition system interactions, network status, and update instructions. Additionally, the guide includes technical specifications in the datasheet and an overview of the Core Box API, featuring documentation, code examples, and usage guidelines.

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Introduction

This guide introduces the Core Box, which is an ECU designed to deliver modular automatic steering solutions for a diverse array of vehicles. Hexagon has tackled the challenges of a fragmented technology landscape, plagued by compatibility and integration issues. The Core Box offers a dependable and precise auto-steering solution seamlessly integrated into the machine's user interface.



Features

Below, you find the key features of the Core Box. Understanding these features will help you fully utilize the Core Box and maximize its benefits.

- **Versatile Connectivity:** Connects through Wi-Fi and mobile data.
- **Powerful Processing:** Equipped with advanced processing capabilities, custom APIs, and complex algorithms, including automatic driving.

- **Standard Protocol Integration:** Compatible with standard protocols such as ISOBUS for ISOBUS VT.
- **Advanced Sensor Suite:** Includes positioning technologies with integrated GNSS, IMU, and multiple inputs for controlling key functions (valves, motors, etc.).
- **Flexible Display Compatibility:** Supports third-party screens and monitors with an agnostic display design.
- **Enhanced Manufacturing Options:** Allows tractor manufacturers to boost shipping demand with factory-installed automatic driving functionality.

Information: The Core Box is available in two variants: Lite and Full, each of them with optional upgrades. These variants are designed to address a range of user needs and application scenarios, providing flexibility and compatibility with various setups and systems. You can find more information in the [Core Box datasheet](#), which will be discussed in the next section.

Datasheet

There's a document titled Core Box Datasheet that contains technical specifications that outline the product's features and capabilities, including details on dimensions, materials, performance, and electrical requirements. Additionally, it offers guidance on how to use the product correctly, including installation instructions. [Click here](#) to access the Core Box datasheet.

Once you have installed Core Box, you can go ahead and learn how to power it on.

Ignition sense

The Core Box does not have a built-in power on/off button in the ECU itself. Instead, it uses the SNSB, which is a digital input that functions as the sensor for powering the system on and off.

For example, when an operator gets to the tractor and wants to start working, they need to turn the machine's key, which creates a high signal. If the SNSB is connected to this sensor, it will detect the high signal, beep, light up the LED, and turn on the system.

The Core Box is equipped with an ignition sense that, when connected to the outlet, activates standby mode. In this mode, the pin must maintain 12 volts to ensure continuous operation. When the device receives an additional pulse, it begins operation. After initialization, the Core Box's operating system becomes active.

Then, it monitors the pin input to detect if the operator has turned the key to turn off the machine. When this happens, a configurable countdown for shutdown begins, with the default being 10 seconds. When the machine is turned off, the signal drops from 12 volts to 0 volts.

Information: Regarding the time required for a safe shutdown, it is recommended to wait approximately 10 to 12 seconds after power loss.

Now that you know how to power on the Core Box, it's time to explore its technical and functional details.

Technical and functional details

You will now explore how LED patterns function, check network status, and learn how to update and format the Core Box.

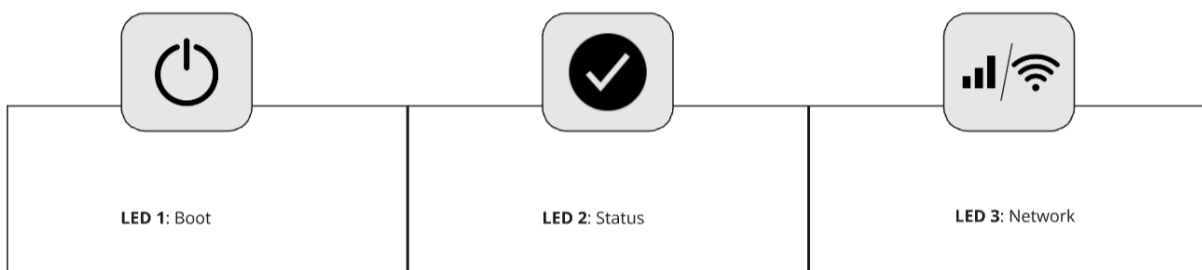
LEDs pattern

The operation can be checked through the three LEDs and internal monotone buzzer present on the device, as shown below:








In this document, the three LEDs will be referred to as LED 1, LED 2, and LED 3.

LED 1 indicates the Core Box's booting status, LED 2 shows the status of the app, and LED 3 represents the network status.



The three LEDs can display five distinct states, including various colors and flashing patterns (whether solid or blinking).

-  Solid green
-  Blinking green
-  Solid red
-  Blinking red
-  Light off

Combined, the 3 LEDs provide information on the following statuses:

- Power status
- Connectivity status
- Alarms

Tip: LED patterns are useful during manual operation, as they provide visual feedback. In autonomous operation, the LED patterns may not be useful.

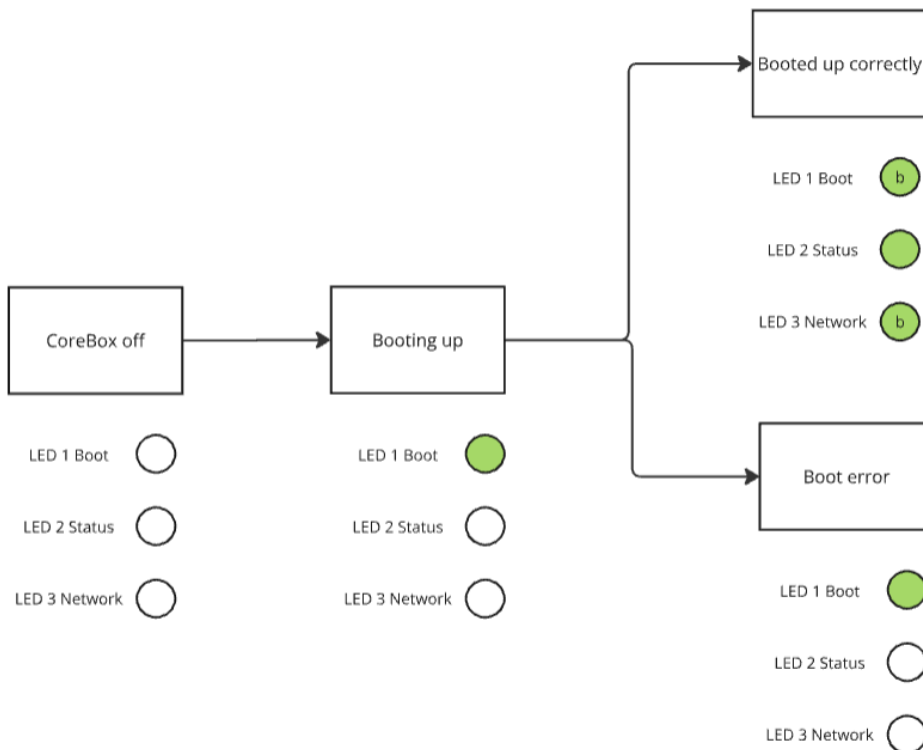
Core Box booting

Now you will learn how to successfully boot the core box. Follow these instructions to ensure a smooth startup process.

1. If the Core Box is powered off, all three LEDs will be off.

2. When you attempt to start it up, LED 1 will light up solid green, while the other two will remain off.
 - a. If the Core Box boots successfully, all three LEDs will turn green: LED 1 and LED 3 will blink, and LED 2 will stay solid green.
 - b. If there's an error during the boot process, LED 1 will be solid green, and the other two LEDs will stay off.




Information: The LED will be solid green when powered through a hardware pull-up and will blink green when the application is active.



App status

The LED signals also indicate the status of the Core Box, whether it's operating correctly, if a diagnostic is in progress, or if it is already available. This applies to any application that fails and generates a diagnostic.




- A solid green LED means that all applications are running smoothly.
- A solid red LED indicates that a diagnostic is available.
- If the LED is blinking red, it signifies that the diagnostic is in progress.

-  All applications running
-  Diagnostic available
-  Diagnostic in progress

Network status

This LEDs provides a general overview of the network status, indicating issues with Wi-Fi or Ethernet connectivity. Besides network issues, the LED will also turn red if there's an internal problem preventing the API from functioning.

- A solid green light indicates a successful connection.
- A blinking green light means it is open for connection.
- A solid red light signals connectivity issues.

-  Connected
-  Open to connection
-  Connectivity Issues

When the Core Box is powered on, the app's status and network connectivity will be signaled by the patterns of the three LEDs.

If the connection is successfully established, the LEDs will display the following behavior:

- LED 1: blinking green
- LED 2: solid green
- LED 3: solid green

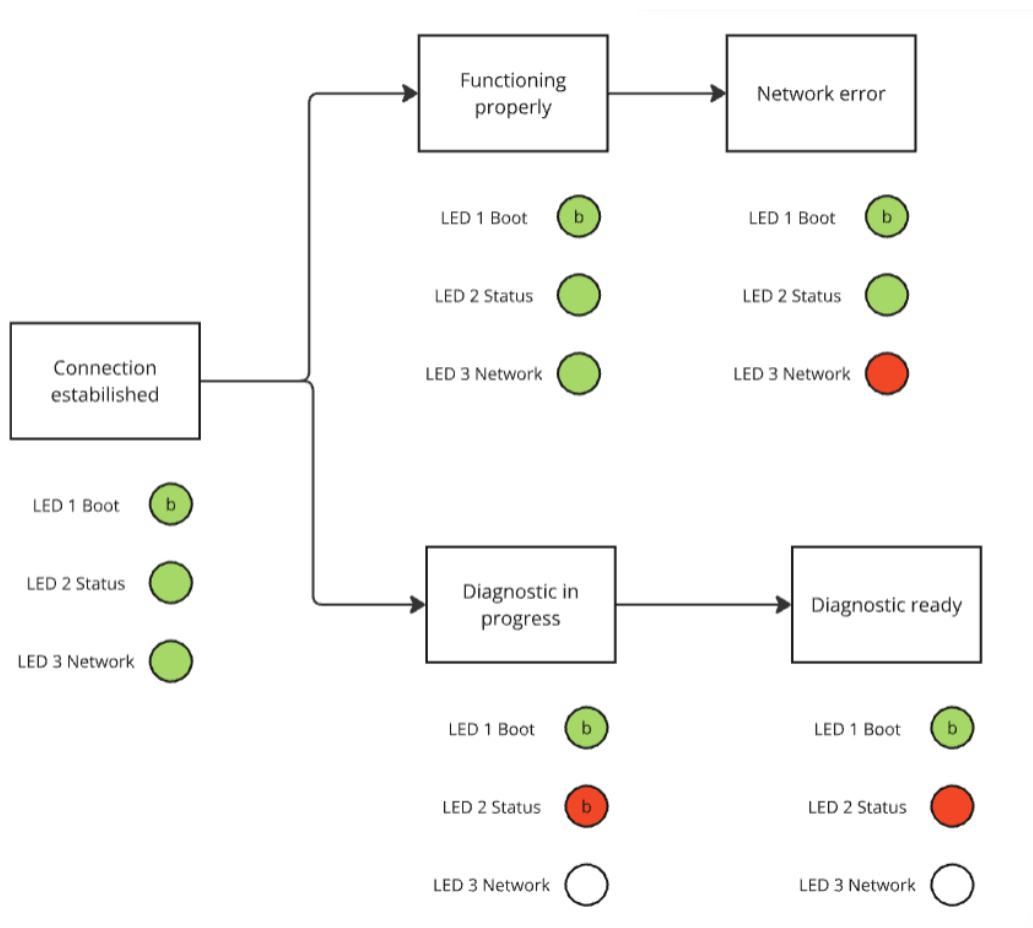
After the connection is established and functioning correctly, the LED behavior remains the same:

- LED 1: blinking green
- LED 2: solid green
- LED 3: solid green

Tip: If a network error occurs after the connection is established, LED 1 will blink green, LED 2 will be solid green, and LED 3 will be solid red.

If the connection is established but does not function correctly, a diagnostic will be initiated to identify the issue.

- During the diagnostic process, LED 1 will blink green, LED 2 will blink red, and LED 3 will be off.
- Once the diagnostic is complete, LED 1 will continue to blink green, LED 2 will display a solid red, and LED 3 will remain off.

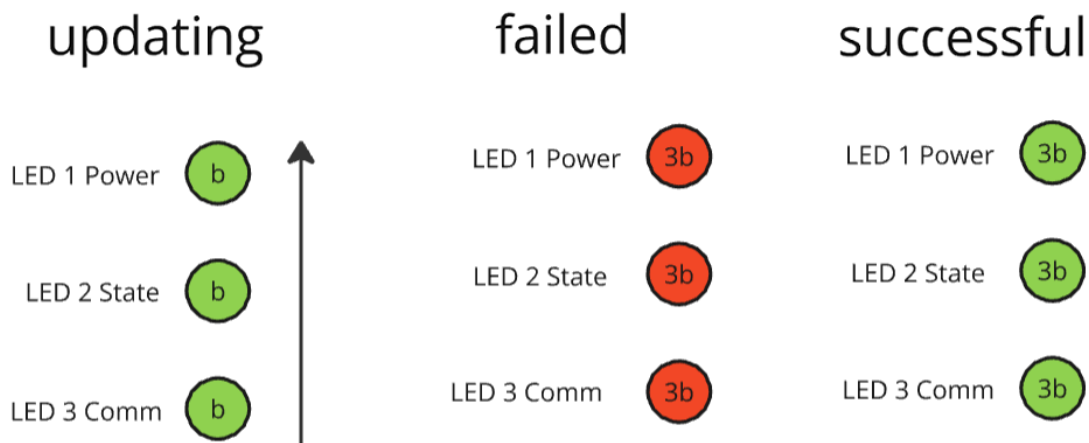


Having learned how to interpret the LED patterns and their meanings, you're now ready to learn how to update and format the Core Box.

Updating and formatting the Core Box

During updates or formatting, the LEDs serve as the primary user interface. They are used to indicate that progress is being made and to signal when the process is complete.

- When updating, it blinks in succession to create a wave effect and resemble a loading bar.
- When the update fails, it blinks three times, like other hardware components. The Core Box will continue to function without interruption and will be ready for another attempt or usage without needing a new update.
- When the update is successful, it blinks three times.



Information: The device beeps when an update is finished, regardless of success or failure, and when formatting is completed. [Click here](#) if you want to learn how to update the Core Box.

Static IP

To connect and configure the Core Box, it's important to note that the Core Box board includes up to 5 internal network interfaces:

- Ethernet 100BASE-TX (Linux interface: eth1)
- Ethernet 100BASE-T1 (automotive Ethernet) (Linux interface: eth0)
- Internal WiFi (Linux interface: wifi0)
- Mobile network module (M2 interface)
- Mobile network module (PCIe interface)

When it comes to static IPs, by default, the Core Box has the following static IPs:

- Static IP **192.168.1.150** on the ethernet interface **eth0**
- Static IP **192.168.1.151** on the ethernet interface **eth1**

Information: You can also use the external connector to attach additional devices such as external WiFi dongles (Linux interface: wifi1) or Ethernet adapters. The connector type to use is M12 Female – 4-pin key D, indicated as connector number four in the image below.



Now that you have explored the Core Box functionalities and specificities, you will learn more about the Core Box external communication API.

Core Box external communication API

The Core Box offers a user-friendly and flexible API that allows users to input the desired path and adjust all necessary system settings. It is designed to enable seamless interaction between the Core Box system and external systems or applications. It provides a structured way to execute commands, transmit data and discover interfaces. Overall, this API allows for efficient management and integration of the Core Box system with other systems or applications, enhancing its functionality and flexibility.

[Click here](#) to learn more about the Core Box external communication API.

Integrating the Core Box with your system

Automatic Steering enables the vehicle to follow a predefined path by identifying the closest point and maintaining the intended trajectory. The system relies on proper path configuration to avoid ambiguity and ensure smooth operation.

The Core Box automatically steer vehicles using paths sent via API. For this, we provide the Point Feed interface, which allows defining and dynamically updating the path to be followed by the Core Box. Below, you will find important information to guide the integration.

Managing paths with the Point Feed in Core Box's Automatic Steering

While Automatic Steering is disengaged, any received path completely replaces the current path.

Information: Only one path is kept in memory, which is identified by a token.

If Automatic Steering is operating, only commands related to the current path (identified by the token) will be accepted, with the purpose of merging them into the current path.

Tip: If the token does not match the current path's token, the command will be rejected.

To extend the current path with new path points, include at least five repeated points from the end of the existing path. If no repeated points are provided or they are too far from the last known point, the command will be rejected, returning code 4 from the Point Feed call.

Warning: After merging a path, already traversed points will be deleted from the memory.

You must ensure that the path is navigable, as the system does not perform any checks based on mechanical or performance constraints. A minimum of four path points is required to create a path.

Information: The Core Box may apply filters to the path in an attempt to smooth it, slightly altering its geometry.

The distance between path points must allow a trajectory reconstruction. In straight segments, a long distance between points is acceptable, while in curves, the tighter the radius, the shorter the distance between points.

Refer to parameter code 2 in the SetParameters method of the Guidance interface. Below are the minimum recommended distances between path points:

- **Straight line:** 2 points, one at the beginning and one at the end
- **Curve with a 15m radius:** 1 point per meter
- **Curve with a 5m radius:** 1 point every 0.25 m

Automatic Steering behavior

When Automatic Steering is engaged, the system determines the trajectory as follows:

- It identifies the closest point on the path relative to the vehicle's current position. This point serves as the starting reference for trajectory tracking, with the direction depending on the vehicle's orientation.

Warning: Avoid sending a path that could create ambiguity in the intended direction.

- With Automatic Steering engaged, the vehicle follows the path in the order of the points, starting from the previously identified point. If Automatic Steering is turned off while on the path and then reactivated, this process will repeat.

Information: Automatic Steering will be disengaged if the end of the path is reached or if the deviation from the path or the angle exceeds the configured values.

Suggested usage

Once the system has been properly calibrated and the GNSS is synchronized, follow the steps below:

1. Avoid sending an initial segment of the path that contains:
 - Joints, nodes, or similar elements;
 - Nearby trajectories that are closer to the vehicle's current position than the intended start of the path;
 - A starting point that is too close to the vehicle's current position.

Tip: Automatic Steering will not engage if the distance and angle relative to the guide exceed the safety parameters configured in the Steering interface (SET/GET parameters method, parameters with ID 10 and 11).

2. Monitor the Guidance signal updates.
3. As the vehicle approaches the end of the path, send new points for the current path using the same token.

Information: The higher the vehicle's speed, the earlier the points should be sent. To ensure smooth processing and error handling, maintain a 30-second buffer before reaching the end of the path.

4. Now that Automatic Steering is already operating, a longer path can be sent, including nodes and joints, and other elements.
5. If Automatic Steering disengages, repeat the process.

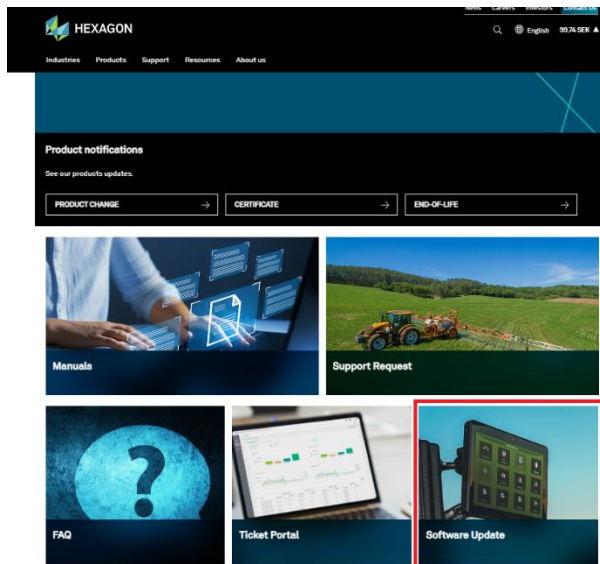
This is all you need to know to start the integration of the Core Box with your system. Next, you will learn how to update the Core Box.

How do I update the Core Box?

To update the Core box software version, you will need a USB flash drive and a .uti file.

Follow the step-by-step instructions:

1. To download the .uti file for the desired version, [click here](#) and access the **Software Update** menu.
2. You will be directed to the **Release Notes**, where you can download the desired version.



Release Notes - Latest display software version



4 Jun 2024



Download version 4.3.0 - T15/T17 - For T15 and T17, it is mandatory to install the latest LTS version here first.
 Download version 4.3.0 - T110 - For T110, formatting is required.

To learn how to update the software version from your display, use this link
 Clique aqui para acessar o release notes em Português

Highlights

This is our newest software version! This version has Hexagon's latest features for agriculture.
 To read this document, consider the symbols used:

Note: This version is recommended for Auto Steering users, specially in rough terrain conditions. In all other cases, we recommend our latest LTS version.

3. Insert the downloaded file into the root directory of a USB flash drive.

Warning: The USB flash drive needs to be formatted in FAT32 for the update to work.

Information: Different files can be downloaded for updates, such as configuration (.cti) and firmware (.ati) updates. It is recommended to insert only one file onto the USB flash drive at a time. If multiple files are present on the drive, the .uti file will be processed before the .cti and .ati files. If there are multiple .uti files, the most recent one will be executed first.

Tip: The Hexagon support team will recommend and share .cti and .ati files with customers as needed.

4. Insert the USB flash drive into the Core Box while it is powered off.
5. Now, power the Core Box on and the update will start automatically.
6. Wait for the update to complete. [Use the LED feedback](#) to understand the status of the update process.
7. Once the update is finished, the Core Box will automatically restart.

Document history

Version	Date	Who	Comments
0.1	27 Sep 2024	Amanda Arrais	First Release.
0.2	12 Feb 2025	Amanda Arrais	Added the section “Integrating the Core Box with your system” and its subsections.